



Rigorous Development of Fault-Tolerant Systems through Co-Refinement

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Motivations

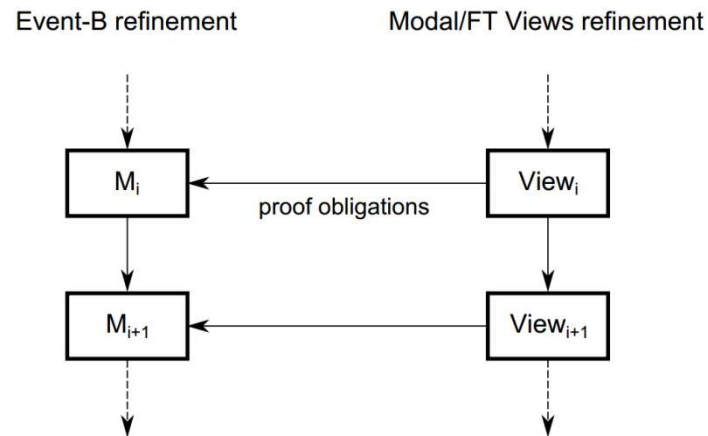
- Tackle systems complexity
- Facilitate industrial acceptance of formal methods
- Improve formalisation of FT requirements
 - High proportion of FT-related requirements to critical systems
 - Fault tolerance requirements are typically intertwined with functional ones
 - Fault assumptions and rigorous definitions of FT requirements rarely make their way to formal models

Introduction

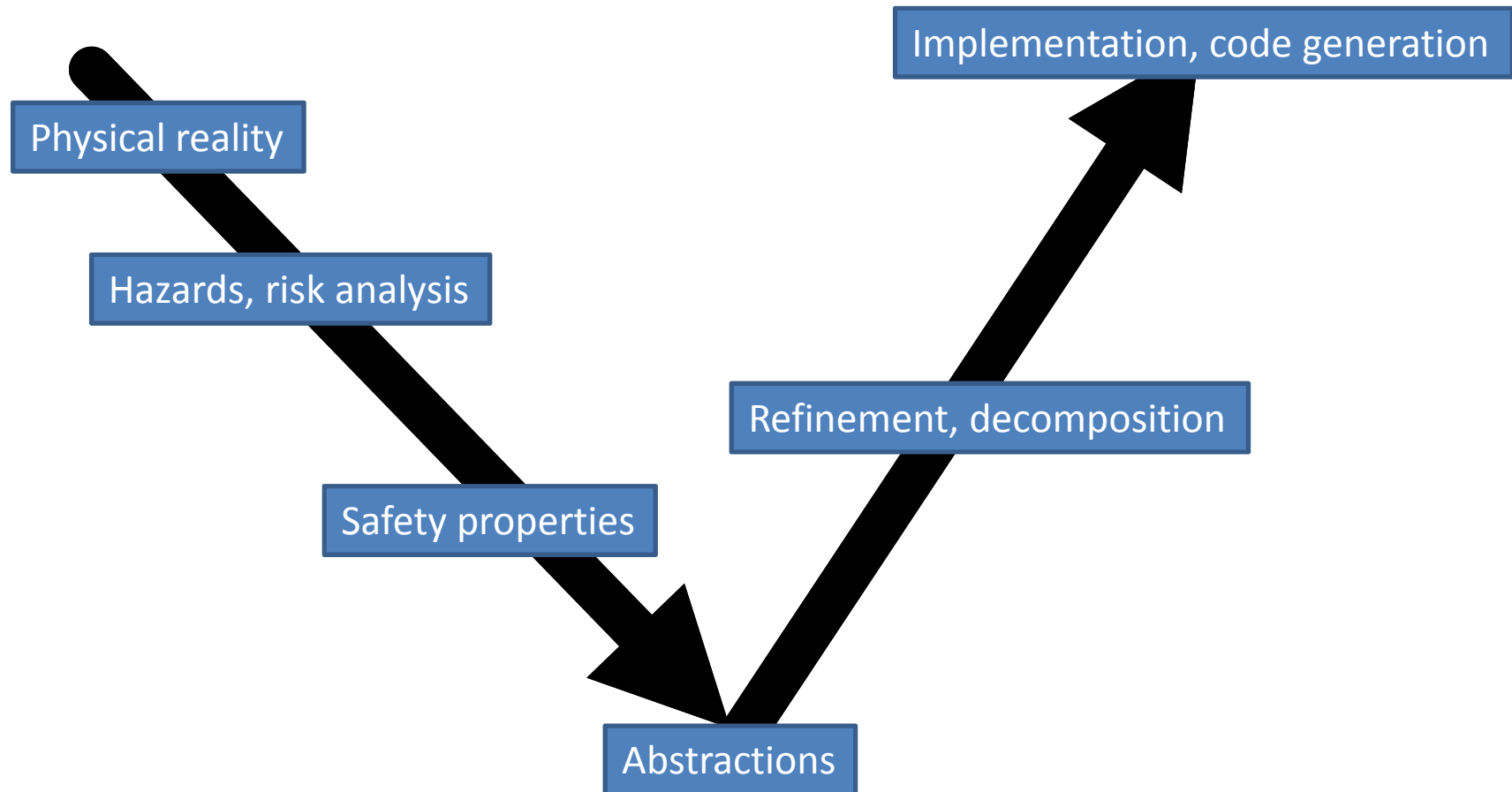
- Refinement
 - Structure complex requirements
 - Correctness-preserving steps
- Separation of concerns & multiple notations
 - Main code vs test cases
 - Process description vs temporal properties
 - State machine vs safety properties
 - UML
 - Multiple views with mutual dependencies

Overview

- Refinement-based formalism (Event-B)
- Diagrammatic formalism (Mode Views)
- Co-refinement
- Focus on proving safety properties



Development process



Constituents

- Modelling principles
- Refinement strategy
- Modelling patterns

Principle

Pattern

Modelling principles

- **Reactive style:** *cause* => *reaction* (properties)
 - *Cause* is typically a state of environment
 - *Reaction* is a system state
- **Behaviour restriction**
 - Start with *unconstrained behaviour*
 - Add *constraints* during refinement

Modelling principles

- **Implementable causality rule** (behaviour)
 - *Cause* (environmental change) must not depend on a *reaction* (system change)
 - Careful with system actions

when door = CLOSED

then sensor = true

- will prove the invariant but won't implement

Modelling principles

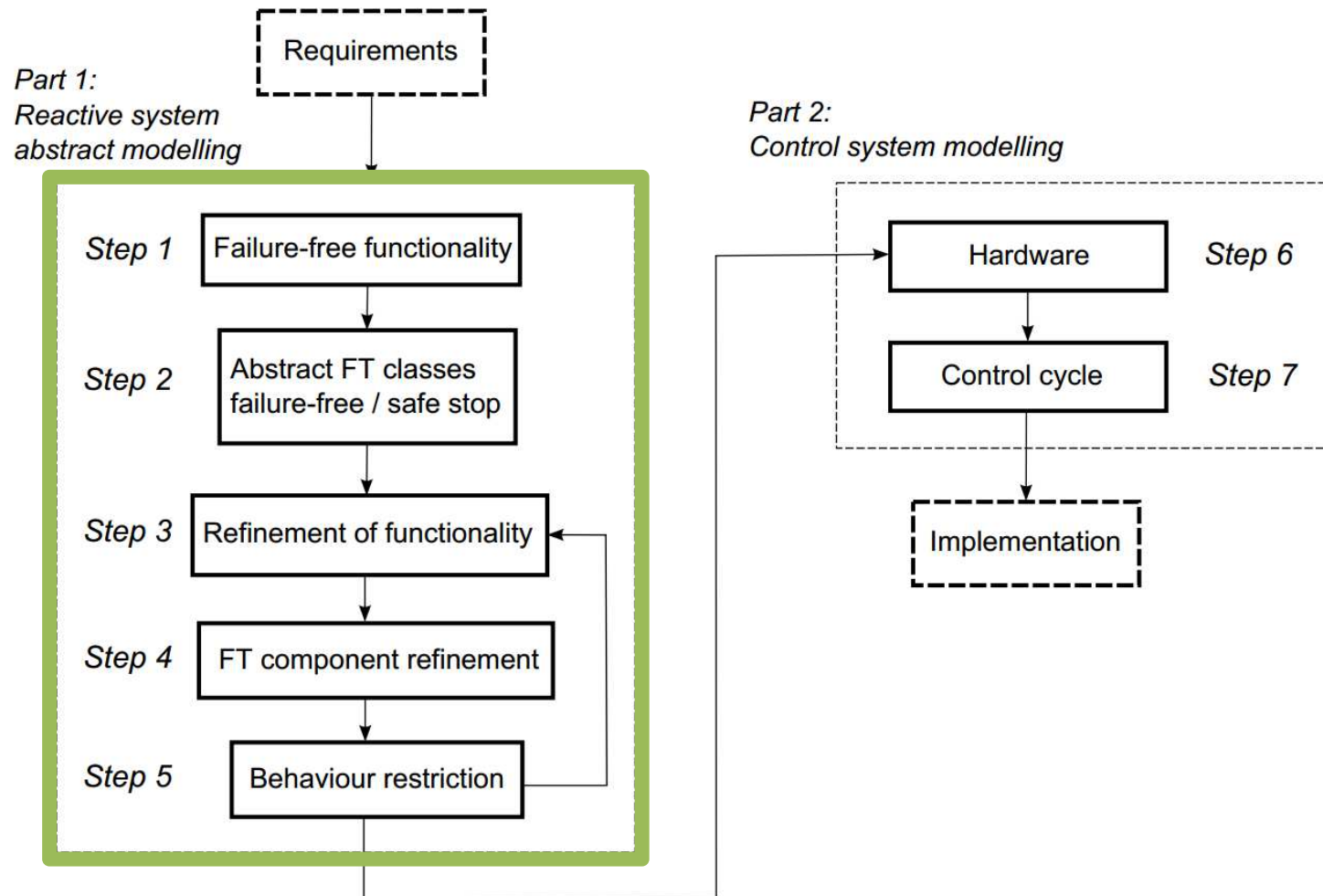
- **Fault tolerant component**

- Structuring mechanism
- Hierarchical definition of system components via *functional* and *error* state variables

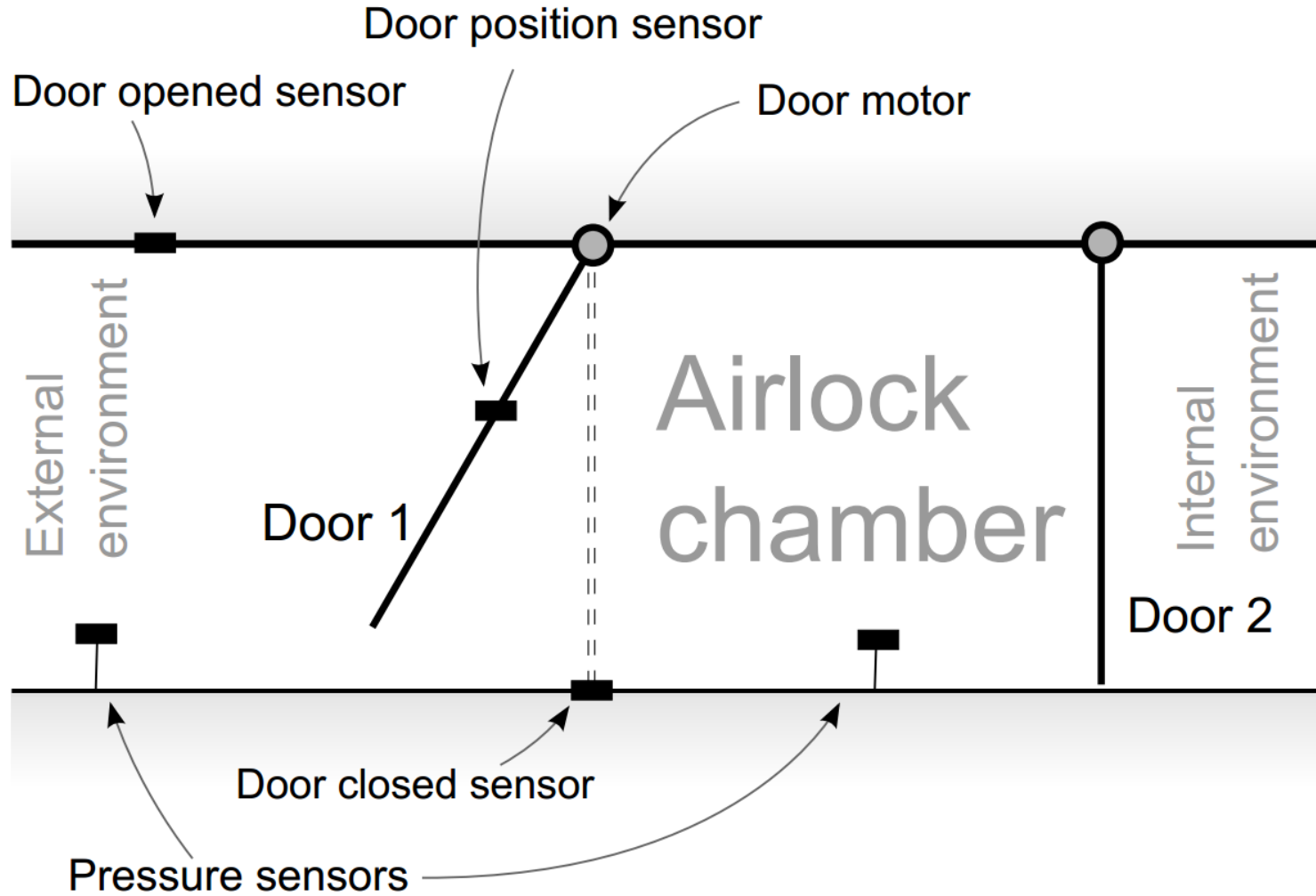
door_state: {OPENED, CLOSED}

door_condition: {OPERATIONAL, BROKEN}

Refinement strategy



Example system



Safety requirements

- (SAF1) The pressure in the chamber must always be between the lower external pressure and the higher internal one
- (SAF2) A door can only be opened if the pressure values in the chamber and the conjoined environment are equal
- (SAF3) At most one door is allowed to be opened at any moment of time
- (SAF4) The pressure in the chamber shall not be changed unless both doors are closed

Failure-free functionality ¹

axioms

axm1: $partition(DOOR_STATE, \{OPENED\}, \{CLOSED\}, \{OPENING\},$
 $\{CLOSING\}, \{STOPPED\})$

axm2: $LOW_PRESSURE = 0$

axm3: $HIGH_PRESSURE = 2$

invariants

inv1: $door1 \in DOOR_STATE$

inv2: $door2 \in DOOR_STATE$

inv3: $pressure \in \mathbb{N}$

inv4: $door1 \neq CLOSED \Rightarrow pressure = LOW_PRESSURE$

inv5: $door2 \neq CLOSED \Rightarrow pressure = HIGH_PRESSURE$

inv6: $door1 = CLOSED \vee door2 = CLOSED$

inv7: $pressure > LOW_PRESSURE \Rightarrow door1 = CLOSED$

inv8: $pressure < HIGH_PRESSURE \Rightarrow door2 = CLOSED$

inv9: $pressure \geq LOW_PRESSURE \wedge pressure \leq HIGH_PRESSURE$

events

event $open1 \hat{=}$

when

grd1: $door1 = CLOSED \vee door1 = STOPPED$

grd2: $pressure = LOW_PRESSURE$

grd3: $door2 = CLOSED$

then

act1: $door1 := OPENING$

end

World

SAF2

SAF3

SAF4

SAF1

Behaviour

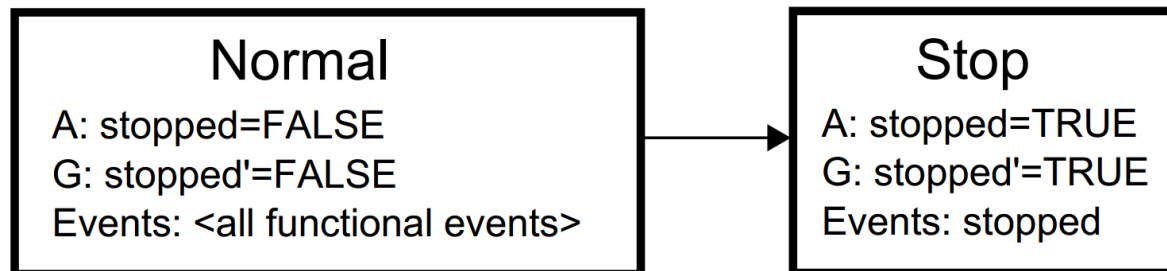
Abstract class of system FT²

```
event open1  $\hat{=}$  extends open1  
  when grd_stopped: stopped = FALSE
```

```
event stop  $\hat{=}$   
  when grd_stopped: stopped = FALSE  
  then act_stopped: stopped := TRUE
```

```
event stopped  $\hat{=}$   
  when grd: stopped = TRUE  
  then skip
```

Safe stop pattern



Safe stop template

FT requirements

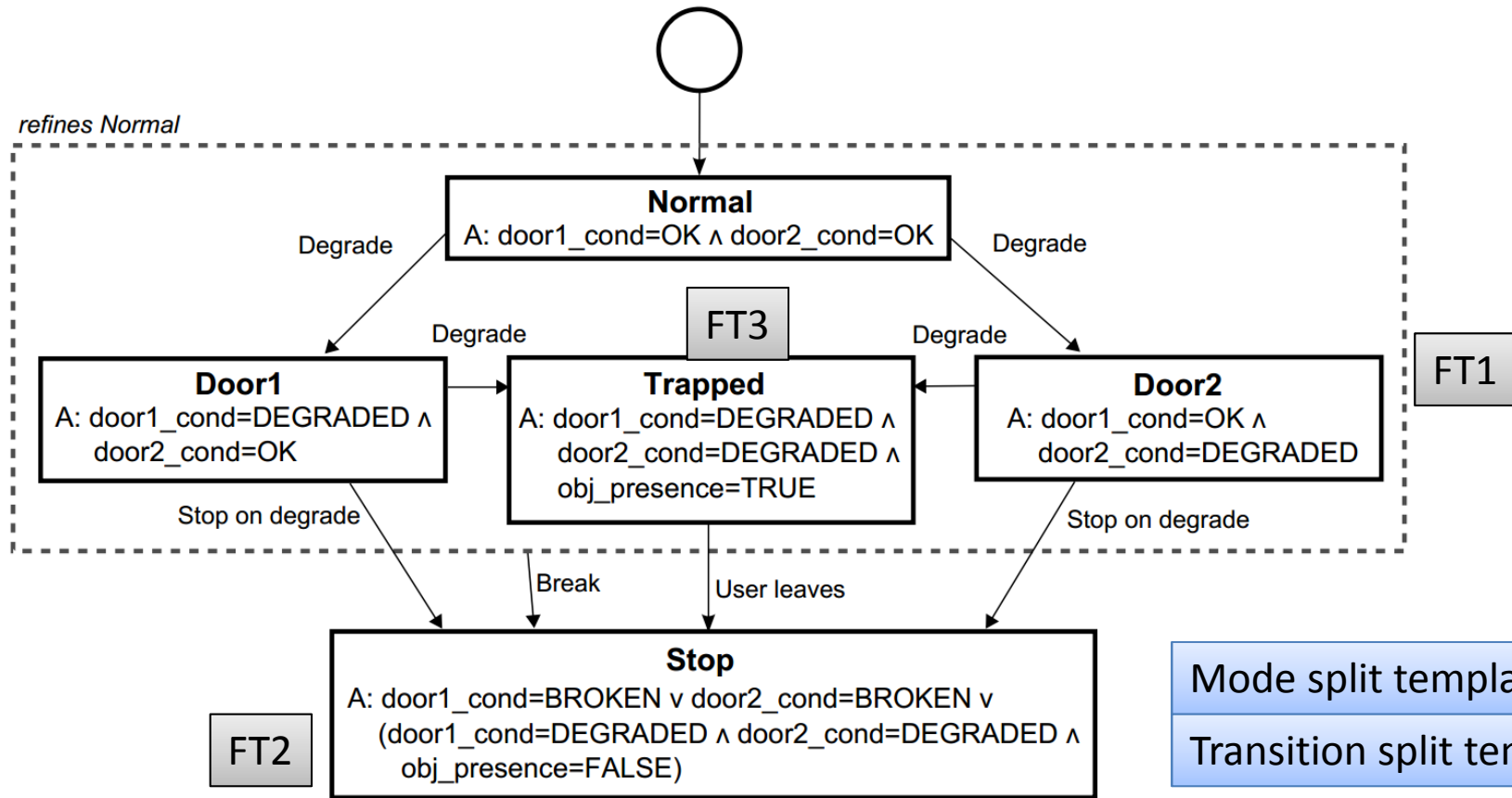
- (FT1) The system shall disallow opening a degraded door
- (FT2) The system shall stop if at least one of the doors is broken
- (FT3) If both doors are degraded, the system shall stop unless there is a user in the chamber. If the user is present in the chamber, the system shall allow opening the inner door

Fault tolerant component refinement

Fault tolerant component

Error state variable

$door1_cond, door2_cond : \{BROKEN, DEGRADED, OK\}$



Mode split template

Transition split template

Fault tolerant component refinement

Error state invariant

$$\begin{aligned} & \text{door1_cond} = \text{BROKEN} \vee \text{door2_cond} = \text{BROKEN} \vee \\ & (\text{door1_cond} = \text{DEGRADED} \wedge \text{door2_cond} = \text{DEGRADED} \wedge \\ & \quad \text{obj_presence} = \text{FALSE}) \Leftrightarrow \text{stopped} = \text{TRUE} \end{aligned}$$

event break $\hat{=}$ extends stop

event degrade $\hat{=}$

event stop_on_degrade $\hat{=}$ extends stop

when

grd1: $\text{door1_cond} = \text{DEGRADED} \vee \text{door2_cond} = \text{DEGRADED}$

grd2: $\text{obj_presence} = \text{FALSE}$

grd4: $\text{door1_cond} = \text{OK} \vee \text{door2_cond} = \text{OK}$

then

act1: $\text{door1_cond} := \text{DEGRADED}$

act2: $\text{door2_cond} := \text{DEGRADED}$

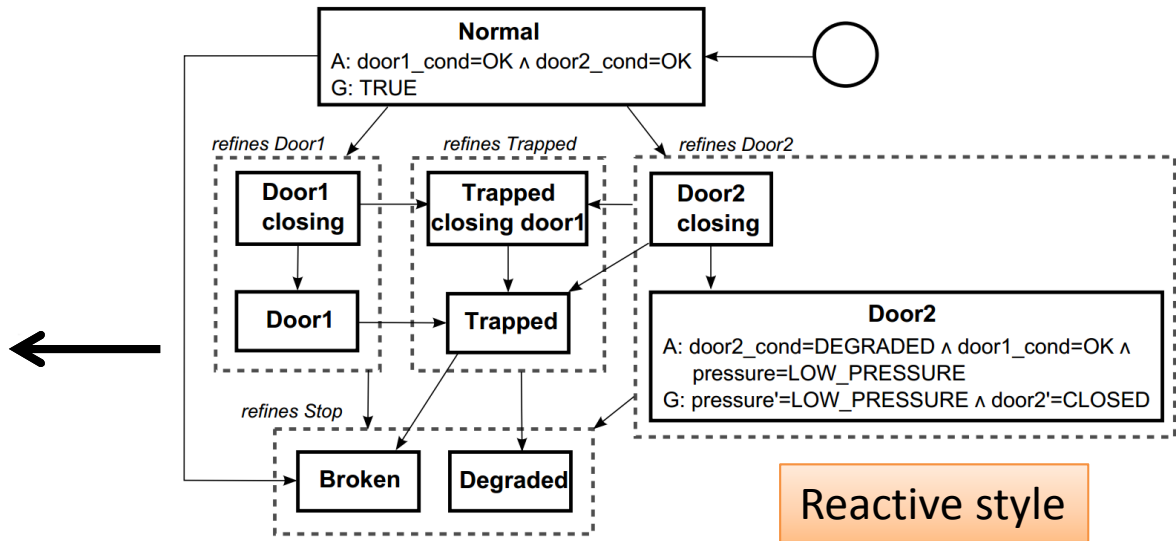
Fault tolerant behaviour

Implementable causality

Behaviour restriction

event open1 $\hat{=}$ extends open1
 when *door1_cond = OK*

Behaviour restriction pattern
 Implementable causality



Low-level features

- ⑥ Sensors, actuators through refinement of fault tolerant components
- ⑥ Environment (who changes pressure?)
- ⑦ Control cycle
 - Implementation

Numbers

- Rodin environment
- 5 Event-B machines
- 3 Modal views
- 356/417 proof obligations proven automatically
- 61 are Event-B POs

Conclusions

- Another medium-scale case study (AOCS) and a number of smaller ones
- Streamlined approach to refinement-based modelling
- Focus on demonstrating safety properties
- Additional viewpoint
 - Adds rigour to the development process
 - Represents system-level FT behaviour
 - Captures FT requirements

Some links

- More details about FT views:

http://wiki.event-b.org/index.php/Mode/FT_Views

- Previous works:

- I. I. Lopatkin. A Method for Rigorous Development of Fault-Tolerant Systems. PhD thesis, Newcastle University, 2013
- II. Lopatkin, A. Iliasov, and A. Romanovsky. Rigorous Development of Dependable Systems using Fault Tolerance Views. ISSRE'11
- III. I. Lopatkin, A. Iliasov, A. Romanovsky, Y. Prokhorova, and E. Troubitsyna. Patterns for Representing FMEA in Formal Specification of Control Systems, HASE'11
- IV. F. L. Dotti, A. Iliasov, L. Ribeiro, and A. Romanovsky. Modal systems: Specification, refinement and realisation, ICFEM '09